

Abstract

A device in a vehicle for monitoring the environment around a vehicle is described, characterized in that objects in a
5 detection range of the sensor system are selected as a function of parameters so that only the selected objects are tracked by the sensor system. This permits adaptive use of reversible restraint means in particular.

10 (Figure 1)

Figure 3 [numbers according to the source diagram]

20 object detection
21 parameter determination
5 22 selection according to parameters
23 tracking of target
24 collision ?
n = no, j = yes
25 restraint means